

Lecture Notes #3: Economic Growth

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Economic Growth: One-Sector Technology

- $Y = C + Z = F(K, L)$
- $C \geq 0, Z \geq 0$
- $\dot{K} = F(K, L) - C - \mu K, \mu > 0$
- $\dot{L} = nL, n > 0$
- $\lambda = \mu + n > 0$
- $y = \frac{Y}{L}, c = \frac{C}{L}, z = \frac{Z}{L}, k = \frac{K}{L}$

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Log differentiating $k = \frac{K}{L}$:

$$\frac{\dot{k}}{k} = \frac{\dot{K}}{K} - \frac{\dot{L}}{L}$$

% change in k = % change in K - % change in L

$$\frac{\dot{k}}{k} = \frac{F(K,L) - C - \mu K}{K} - n$$

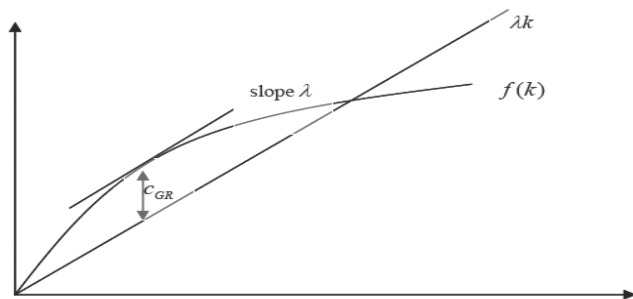
$$\dot{k} = \frac{(K/L)(F(K,L) - C - \mu K)}{K} - nk$$

$$\dot{k} = f(k) - c - \lambda k$$

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- $\dot{k} = 0$ defines the steady state (in which K and L are growing at the same rate).
 $\dot{k} = 0$ is also the stationary solution to the DE $\dot{k} = 0$
- In the steady state we have:
$$c = f(k) - \lambda k$$
Hence for steady-state production c is a function of k :
$$c(k) = f(k) - \lambda k$$
- We next study by graphing and calculus $c(k)$
We will find the golden rule k discovered by Edmund S. (Ned) Phelps

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- Golden Rule Capital Labor Ratio, k_{GR} , maximizes consumption across steady states.
- $f'(k_{GR}) = \lambda$
- $r = f'(k) - \mu$

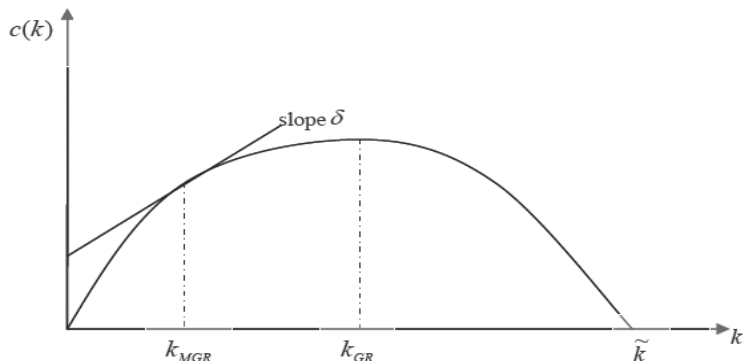
$r_{GR} = n$ rate of interest=growth of labor

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- $c(k) = f(k) - \lambda k$
 $\frac{dc}{dk} = f'(k) - \lambda$
 $f'(k_{GR}) - \mu = n$
 $r_{GN} = N$
- $\frac{d^2c}{dk^2} = f'' < 0$ 2nd order condition
- Modified Golden Rule:
 $f'(k_{MGR}) = \delta + \lambda$
David Cass

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another graph



- δ positive in this graph
- \tilde{k} is the maximal sustainable capital-labor ration: $c(\tilde{k}) = 0$
over-saving !

Meaning of GR

- Not necessarily "optimal"
 - Initial k is not given
 - What use is it to advise country with very low k to choose k_{GR} ?
 - Why should one want to go to a steady state even if feasible ?
 - optimal growth later !
- Efficiency:
While $\{k(t)\}$ always small can be efficient, $\{k(t)\}$ "too large" will be inefficient. Oversaving ! Because of infinite horizon

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- Phelps-Koopmans Inefficiency Theorem

If $\{k(t)\}$ is forever bounded above k_{GR} , then the program $\{k(t), c(t)\}$ is inefficient in the sense that $c(t)$ can be increased in some intervals without decreasing $c(t)$ elsewhere

- Definitions:

Consider the feasible program:

$$\{c(t) \mid c(t) \leq f(k(t)) - \lambda k(t) - \dot{k}(t), k(0) \leq k_0, t \in [0, \infty]\}$$

The program is said to be inefficient if there exist $c'(t)$ and $k'(t)$ with the properties:

$$\{c'(t) \mid c'(t) \leq f(k'(t)) - \lambda k'(t) - \dot{k}'(t), k'(0) \leq k_0, t \in [0, \infty]\}$$

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and

$$c'(t) \geq c(t) \quad \text{for } t \in [0, \infty]$$

while

$$c'(t) > c(t) \quad \text{for some interval } [t_1, t_2] \subset [0, \infty], t_1 < t_2$$

Proof of the KP Theorem:

assume that after some date $t^* \geq 0$, $k(t) > k_{GR} + \varepsilon$ for some (small) $\varepsilon > 0$. Then we can construct $k'(t)$ from $k(t)$

$$k'(t) = k(t) \text{ for } t \in [0, t^*]$$

$$k'(t) = k(t) - \varepsilon \text{ for } t \geq t^*$$

$$c'(t) = f(k'(t)) - \lambda k'(t) = f(k(t) - \varepsilon) - \lambda(k(t) - \varepsilon) > c(t)$$

Descriptive Growth (Solow)

Reference:

- R. M. Solow, "A Contribution to the Theory of Economic Growth", Quarterly Journal of Economics, February 1956

composite of output (C, Z) determined be exogenously
given saving functions, $s > 0$

$$Z = sY$$

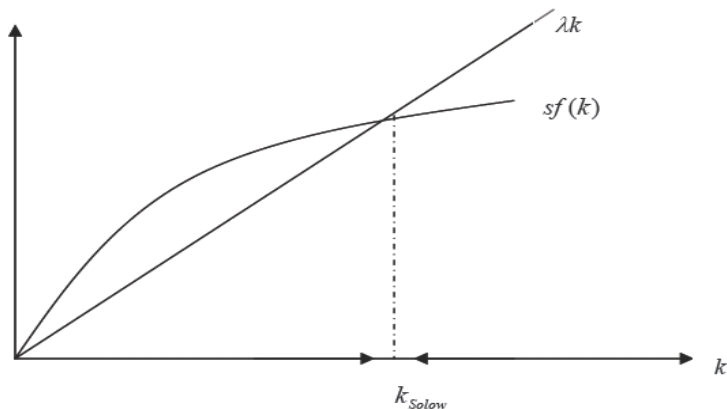
$$C = (1 - s)Y$$

$$\dot{k} = f(k) - \lambda k$$

$$k(0) = k_0 > 0$$

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Phase Line



More generally, Phase Diagrams for all dynamical systems including differential equations and difference equations

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- Solow model is locally stable and globally stable if we assume $k_0 > 0$.
0 is unstable
- History independence. Neither a good thing nor a bad thing.
QWERTY
Massachusetts vs New York
Railroad crossing

Reference:

- 1. D. Cass, "Optimum Growth in an Aggregative Model of Capital Accumulation," *Review of Economic Studies*, July 1965.
- 2. Shell's Varenna Lectures (1969)

Problem will be to choose $\{0 \leq s(t) \leq 1\}$ to maximize

$$\int_0^T U(c(t))e^{-\delta t} dt$$

where $c(t) = (1 - s(t))f(k(t))$

$$\dot{k} = s(t)f(k(t)) - \lambda k(t)$$

where $k(0) = k_0$ and $k(T) = k_T$,

First also assume (for the moment) that $T < \infty$ is finite

Calculus of Variations and the Euler Equation

- Problem is to find a best function, not merely a best point.
- Consider $x(t)$ defined on $[t_0, t_1]$ and $x(t_0) = x_0$, $x(t_1) = x_1$ and to extremize the integrand $\int_{t_0}^{t_1} \Phi(x(t), \dot{x}(t), t) dt$
- Euler's necessary condition is that $\Phi_x = \frac{d}{dt} \Phi_{\dot{x}}$ be satisfied.

Derivation:

Consider $y(t, \varepsilon) = x(t) + \varepsilon u(t)$ to be a variation of the function $x(t)$.

$$V(\varepsilon) = \int_{t_0}^{t_1} \Phi(x(t) + \varepsilon u(t), \dot{x}(t) + \varepsilon \dot{u}(t), t) dt$$

$$V'(\varepsilon) = \int_{t_0}^{t_1} (u(t)\Phi_y + \dot{u}(t)\Phi_{\dot{y}}) dt = 0$$

Integrate by parts:

$$\begin{aligned} \int_{t_0}^{t_1} \dot{u}(t)\Phi_{\dot{y}} dt &= u\Phi_{\dot{y}} \Big|_{t_0}^{t_1} - \int_{t_0}^{t_1} u \left(\frac{d}{dt} \Phi_{\dot{y}} \right) dt \\ &= 0 - 0 - \int_{t_0}^{t_1} u \left(\frac{d}{dt} \Phi_{\dot{y}} \right) dt = - \int_{t_0}^{t_1} u \left(\frac{d}{dt} \Phi_{\dot{y}} \right) dt \end{aligned}$$

Optimal Growth

So $\int_{t_0}^{t_1} u(\Phi_y - (\frac{d}{dt}\Phi_{\dot{y}}))dt = 0$.

This must hold for every function $u(t)$.

Hence we have $\Phi_y = (\frac{d}{dt}\Phi_{\dot{y}})$ or $\Phi_x = \frac{d}{dt}\Phi_{\dot{x}}$

Apply to one-sector RCK problem assuming, one can eat capital and further no corner conditions are involved.

$$\int_0^{\infty} U(f(k) - \lambda k - \dot{k}) e^{-\delta t} dt$$
$$\Phi_k = U' \cdot (f'(k) - \lambda) e^{-\delta t}$$
$$\Phi_{\dot{k}} = -U' e^{-\delta t}$$

Optimal Growth

Let $q = U'$ be the current demand price k and $qe^{-\delta t}$ the present demand price of k . Then we have:

$$q \cdot (f'(k) - \lambda)e^{-\delta t} = \frac{d}{dt}(-qe^{-\delta t}) = -\dot{q}e^{-\delta t} + \delta qe^{-\delta t}$$

$$\dot{q} = q(f'(k) - \lambda - \delta)$$

$$\dot{k} = f(k) - \lambda k - c(q)$$

where $U'(c) = q$

Hence $\frac{dq}{dc} = U''(c) < 0$ and $\frac{dc}{dq} = \frac{1}{U''(c)} < 0$

Stationeries:

$\dot{q} = 0$ yields $f'(k) = \delta + \lambda$ call root k^* *MGR* k

$\dot{k} = 0$ yields

$$c(q) = f(k) - \lambda k$$

$$c'(q) \frac{dq}{dk} = f'(k) - \lambda$$

$\frac{dq}{dk} = (f'(k) - \lambda) U''$ achieves minimum at k_{GR}

Phase diagram next:

Optimal Growth

RCK phase diagram

